

FIG. 2

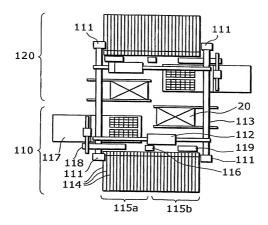


FIG. 3

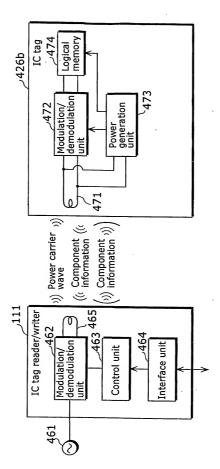
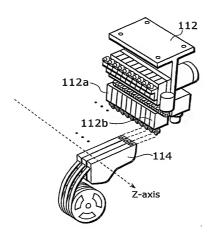
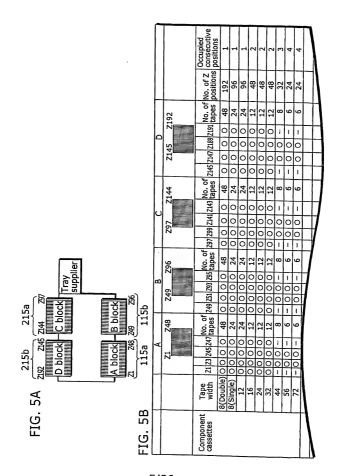


FIG. 4





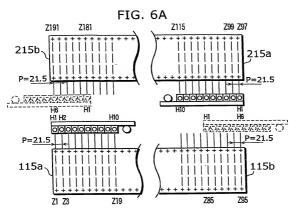


FIG. 6B

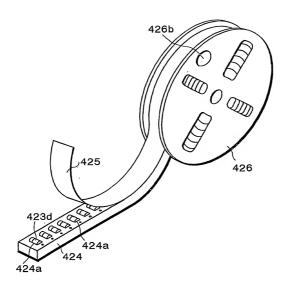
heads	Inner side	Z1 Z2	Z3 Z4	Z5 Z6	Z7 Z8	Z9 Z10	Z11 Z12	Z13 Z14	Z15 Z16		Z19 ~ Z86	Z87 Z88	Z89 Z90	Z91 Z92	Z93 Z94	Z95 Z96
	Outer side	Z97 Z98			Z103 Z104					Z113 Z114	Z115 ~ Z182	7104	Z185 Z186	Z187 Z188	Z189 Z190	Z191 Z192
	H1	0	0	0	0	0	0	0	0	0	0			1		_
	H2	=	0	0	0	0	0	0	0	0	0	0	-	_	_	-
	НЗ	-	-	0	O	0	0	0	0	0	0	0	0	-	_	_
	H4	-	-	-	0	0	0	0	0	0	0	0	0	0	-	_
Heads	H5	=	-	=	-	0	0	0	0	0	0	0	0	0	0	_
(Nozzles)	H6	=	-	-	-	-	0	0	0	0	0	0	0	0	0	0
	H7	-	-	-	-	Ε	-	0	0	0	0	0	0	0	0	0
	H8	-	1-	-	-	 -	-	T-	0	0	0	0	0	0	0	0
	H9	-	1-	-	-	-	T	Ι-	-	0	0	0	0	0	0	0
	H10	<u> </u>	-	1-	_	<u> </u>	1-	[=	1-	1-	0	0	0	10	0	0

O: Picking up possible-: Picking up impossible

FIG. 7A FIG. 7B FIG. 7C FIG. 7D

123a 423b 423c

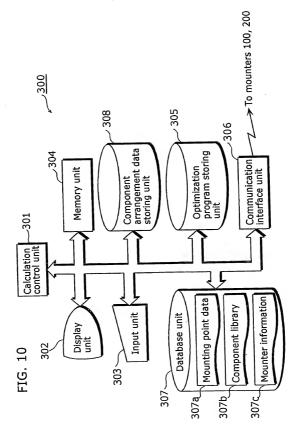
FIG. 8



426b 114 434 436 426 430 424 433 425 427

429 432

FIG. 9



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FTG. 1.

307a

Mounting points pi=(Component type Ci, X coordinate Xi, Y coordinate Yi, Control data ϕ i)

NC data is a list of mounting points pi

NC data = $\begin{pmatrix} p_1 \end{pmatrix} = \begin{pmatrix} c_1, x_1, y_1, \phi & 1 \\ c_2, x_2, y_2, \phi & 2 \\ p_3 & c_3, x_3, y_3, \phi & 3 \\ \vdots & \vdots & \vdots \\ p_N & c_N, x_N, y_N, \phi & N \end{pmatrix}$

FIG. 12

				. 10	. 12	307b			
Component name	(Appea- rance)	Size (IIIIII)			2-D recognition	Pick-up	Tact time	Speed	
name	rance)	Х	Υ	L	method	nozzle	(sec.)	XY	
0603CR		0.6	0.3	0.25		SX	0.086		
1005CR		1.0	0.5	0.3-0.5		SA	0.086		
1608CR	*	1.6	0.8	0.4-0.8			0.094	1	
2012CR		2.0	1.25	0.4-0.8		s			
3216CR		3.2	1.6	0.4-0.8		5	}	1	
4TR		2.8	2.8	1.1				1	
6TR	₩	4.3	4.5	1.5					
1TIP	ODD	2.0	φ1.0	-		Cylindrical			
2TIP	012	012	3.6	φ1.4	-		tip	0.11	
1CAP		3.8	1.9	1.6		-			
2CAP		4.7	2.6	2.1		S	ļ		
3CAP	-	6.0	3.2	2.5					
4CAP		7.3	4.3	2.8	Reflection	М			
SCAP		4.3	4.3	6.0		141			
LCAP		6.6	6.6	6.0					
LLCAP		10.3	10.3	10.5		ML			
1VOL		4.5	3.8	1.6-2.4					
2VOL		3.7	3.0	1.6		М	0.13	2	
3VOL		4.8	4.0	3.0			0.10	_	

FIG. 13

√307c

Unit ID	Head information	Nozzle information	Cassette information	Tray information	
110	10 nozzle heads	SX,SA,···	96	8 levels	
120	10 nozzle heads	None	96	None	
210	4 nozzle heads	S,M,	48	None	

FIG. 14

Component name	Unit ID	Z number	
0603CR	110	5	
1005CR	120	8	
1608CR	210	4	
2012CR	120	22	

FIG. 15

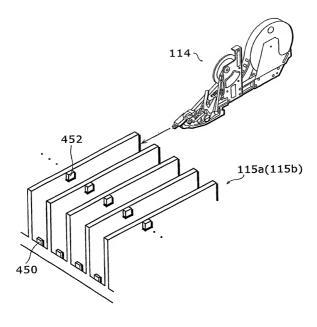


FIG. 16

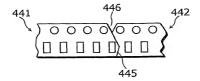
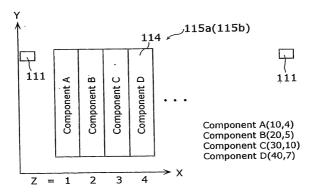


FIG. 17



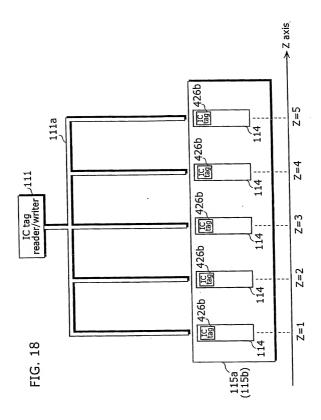


FIG. 19 Start S11A NO Has component cassette been set? YES S12A Specify Z number of component cassette that has been set according to information from switch 450 S13 Obtain information about components that have been set S14 NO Has correct component cassette been set? S,15 YES Warning End

FIG. 20 Start **S11B** NO Has component cassette been set? YES S12B Specify Z number of component cassette that has been set according to signal from IC tag readers/writers 111 S13 Obtain information about component tape that has been set S14 NO Has correct component cassette been set? S15 YES Warning End

FIG. 21

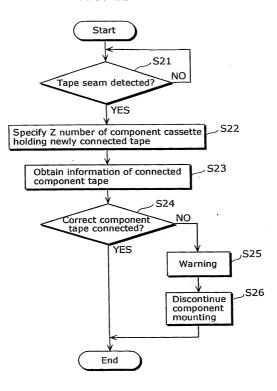
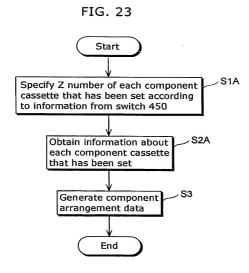
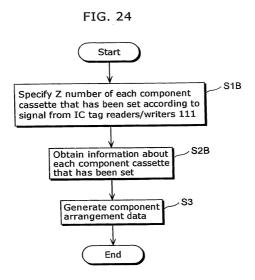


FIG. 22 Start S31 NO Component mounting? YES Decrement remaining S32 number of components ×S33 Write manufacturing information S34 NO Remaining number of components<threshold? YES S35 Warning ,S36 NO Remaining number of components=0? YES S37 Discontinue component mounting End

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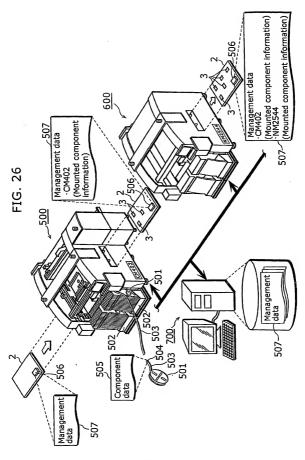


Specify Z number of component cassette that has been set

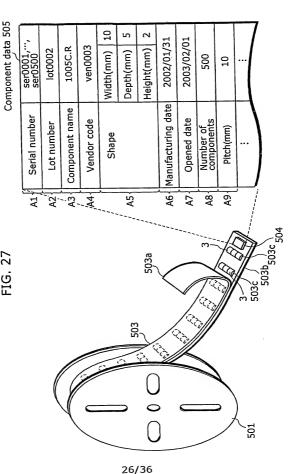
Obtain information about component cassette that has been set

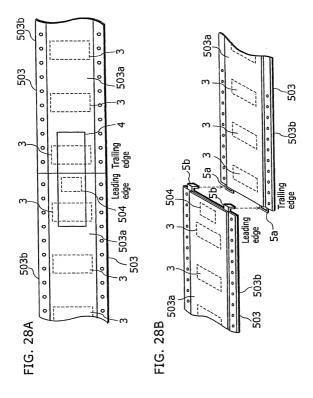
Generate component library

End



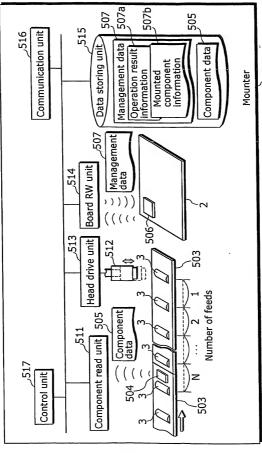
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20,



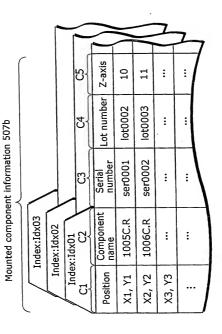


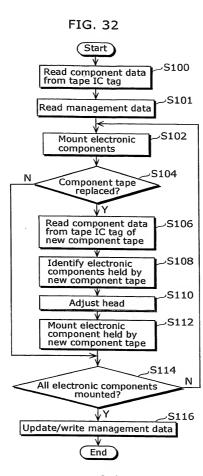
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FIG. 30

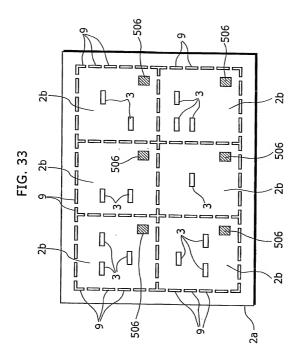
a a	_					,
Operation result information 507a	B6		Index	Idx 01	i	:
0.5			Step	100	:	:
	95	Error	Code	MC0005	:	
			Date/time of	CM402 2003/01/06 35 sec PTESTA 2003/01/06 MC0005	:	:\
	8		<u>8</u>	PTESTA	:	:
	₹ B3		Tact	35 sec	:	:
Board ID:PB011D/	number:PB01k B2		Machine Date/time	2003/01/06	:	1
Boar	/ Lot r B1		Machine	CM402	NM2544	

FIG. 31





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504

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FIG. 35

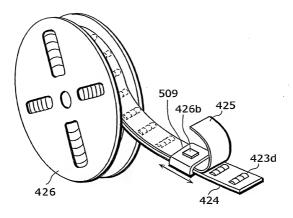


FIG. 36

